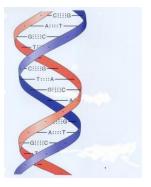
## Motivation for Sublinear-Time Algorithms

#### Massive datasets

- world-wide web
- online social networks
- genome project
- sales logs
- census data
- high-resolution images
- scientific measurements
- Long access time
- communication bottleneck (slow connection)
- implicit data (an experiment per data point)

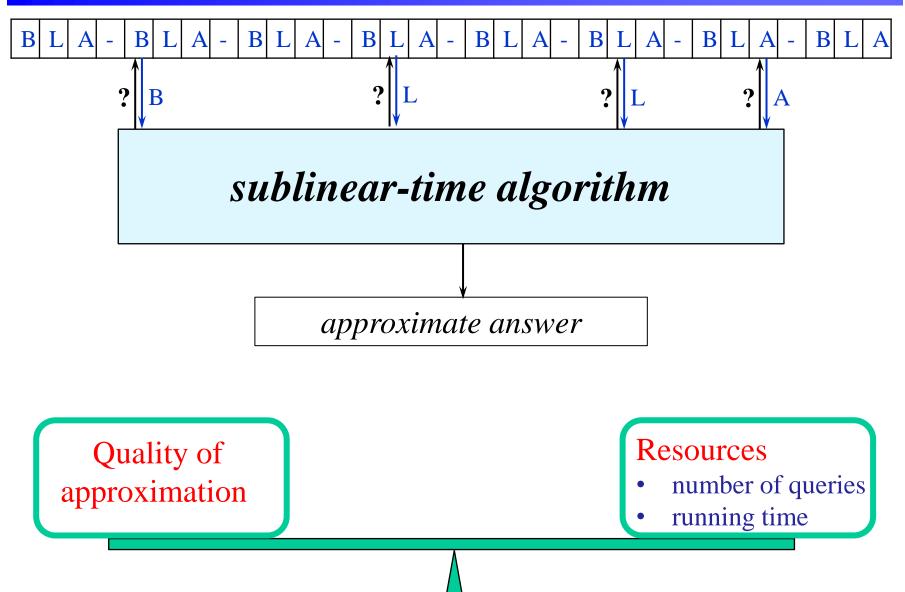




#### What Can We Hope For?

- What can an algorithm compute if it
  - reads only a sublinear portion of the data?
  - runs in **sublinear** time?
- Some problems have exact deterministic solutions
- For most interesting problems algorithms must be
  - approximate
  - randomized

#### A Sublinear-Time Algorithm



## Types of Approximation

#### **Classical approximation**

- need to compute a value
  - output should be close to the desired value
  - example: average

#### **Property testing**

need to answer YES or NO

Intuition: only require correct answers on two sets of instances that are very different from each other

## Classical Approximation

## A Simple Example

#### Approximate Diameter of a Point Set [Indyk]

Input: *m* points, described by a distance matrix *D* 

- $D_{ij}$  is the distance between points *i* and *j*
- D satisfies triangle inequality and symmetry (Note: input size is  $n = m^2$ )
- Let *i*, *j* be indices that maximize  $D_{ij}$ . Maximum  $D_{ij}$  is the *diameter*.
- Output:  $(k, \ell)$  such that  $D_{k\ell} \ge D_{ij}/2$

#### Algorithm and Analysis

Algorithm (m, D)

- 1. Pick k arbitrarily
- 2. Pick  $\ell$  to maximize  $D_{k\ell}$
- 3. Output  $(k, \ell)$
- Approximation guarantee  $D_{ij} \leq D_{ik} + D_{kj}$  (triangle inequality)  $\leq D_{k\ell} + D_{k\ell}$  (choice of  $\ell$  + symmetry of D) k $\leq 2Dk_{\ell}$
- Running time:  $O(m) = O(m = \sqrt{n})$

A rare example of a deterministic sublinear-time algorithm

# Property Testing

#### **Property Testing: YES/NO Questions**

#### Does the input satisfy some property? (YES/NO)

#### "in the ballpark" vs. "out of the ballpark"

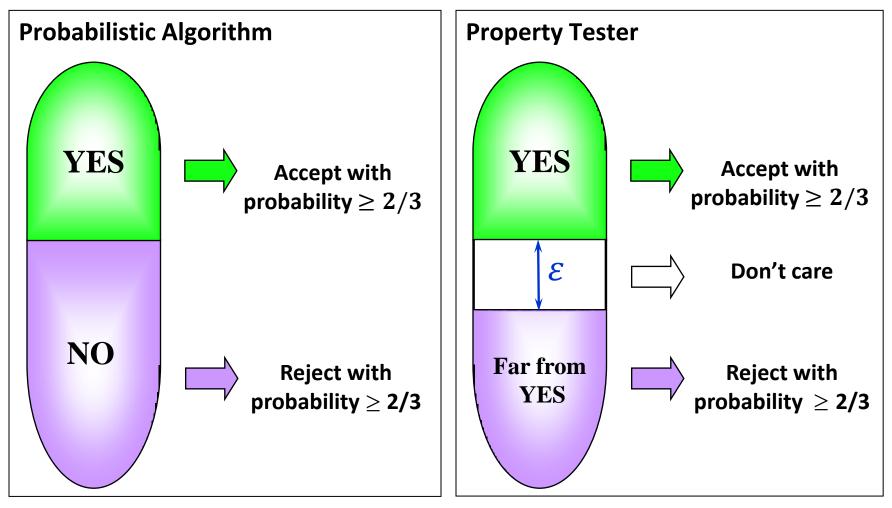




#### Does the input satisfy the property or is it far from satisfying it?

- sometimes it is the right question (probabilistically checkable proofs (PCPs))
- as good when the data is constantly changing (WWW)
- fast sanity check to rule out inappropriate inputs (airport security questioning)

#### **Property Tester Definition**



 $\varepsilon$ -far = differs in many places ( $\geq \varepsilon$  fraction of places)

# Randomized Sublinear Algorithms

Toy Examples

#### **Property Testing: a Toy Example**

Input: a string  $w \in \{0,1\}^n$ 

Question: Is  $w = 00 \dots 0$ ?

Requires reading entire input.

Approximate version: Is  $w = 00 \dots 0$  or

does it have  $\geq \varepsilon n$  1's ("errors")?

1

 $\mathbf{O}$ 

()

 $\mathbf{0}$ 

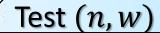
1

 $\mathbf{O}$ 

0

...

Used:  $1 - x \le e^{-x}$ 



1. Sample  $s = 2/\varepsilon$  positions uniformly and independently at random

2. If 1 is found, **reject**; otherwise, **accept** 

Analysis: If  $w = 00 \dots 0$ , it is always accepted.

If w is  $\varepsilon$ -far, Pr[error] = Pr[no 1's in the sample]  $\leq (1-\varepsilon)^s \leq e^{-\varepsilon s} = e^{-2} < \frac{1}{2}$ 

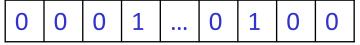
#### Witness Lemma

If a test catches a witness with probability  $\geq p$ ,

then  $s = \frac{2}{p}$  iterations of the test catch a witness with probability  $\geq 2/3$ .

#### Randomized Approximation: a Toy Example

Input: a string  $w \in \{0,1\}^n$ 



Goal: Estimate the fraction of 1's in w (like in polls)

It suffices to sample  $s = 1 / \epsilon^2$  positions and output the average to get the fraction of 1's  $\pm \epsilon$  (i.e., additive error  $\epsilon$ ) with probability  $\geq 2/3$ 

# Hoeffding BoundLet $Y_1, ..., Y_s$ be independently distributed random variables in [0,1] andlet $Y = \sum_{i=1}^{s} Y_i$ (sample sum). Then $\Pr[|Y - E[Y]| \ge \delta] \le 2e^{-2\delta^2/s}$ . $Y_i$ = value of sample i. Then $E[Y] = \sum_{i=1}^{s} E[Y_i] = s \cdot (\text{fraction of 1's in } w)$ $\Pr[|(\text{sample average}) - (\text{fraction of 1's in } w)| \ge \varepsilon] = \Pr[|Y - E[Y]| \ge \varepsilon s]$ $\le 2e^{-2\delta^2/s} = 2e^{-2} < 1/3$ Apply Hoeffding Bound with $\delta = \varepsilon s$

# Property Testing

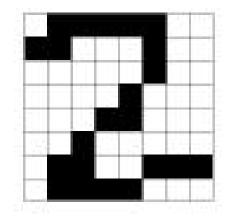
## Simple Examples

#### **Testing Properties of Images**



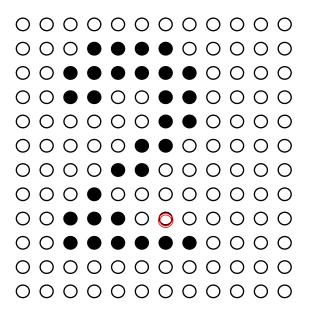






#### Pixel Model

Input:  $n \times n$  matrix of pixels (0/1 values for black-and-white pictures)

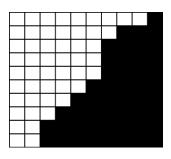


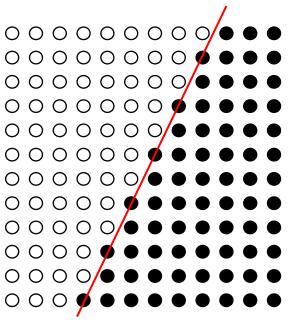
Query: point  $(i_1, i_2)$ Answer: color of  $(i_1, i_2)$ 

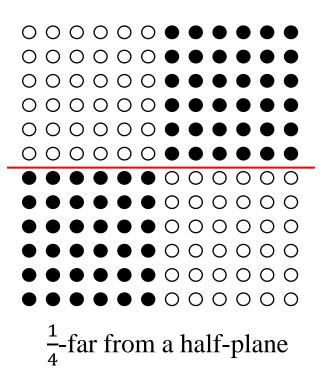
#### Testing if an Image is a Half-plane [R03]

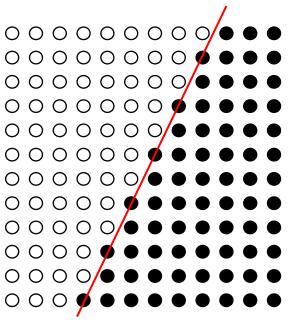
A half-plane or  $\varepsilon$ -far from a half-plane?

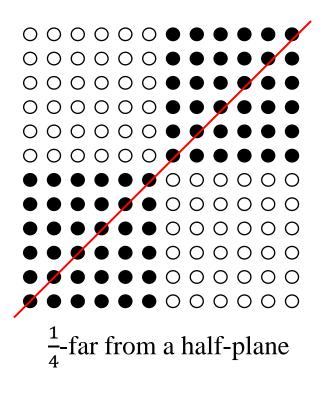
 $O(1/\varepsilon)$  time

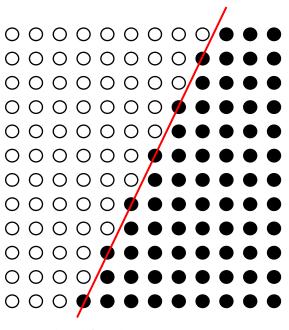


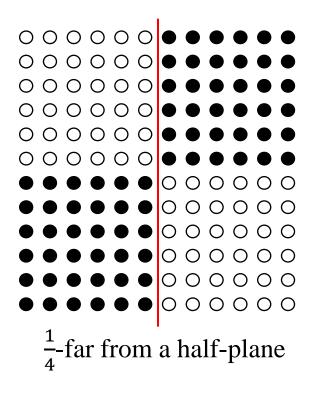


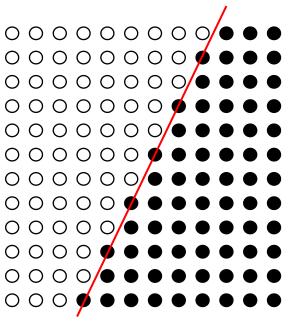


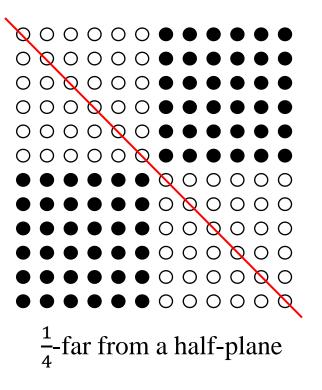


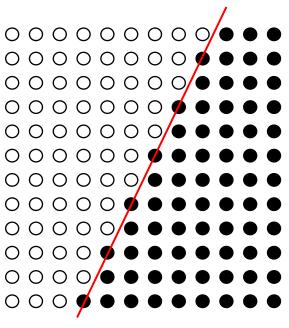


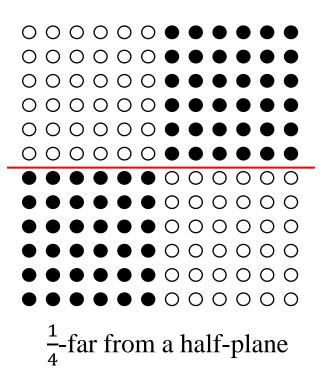


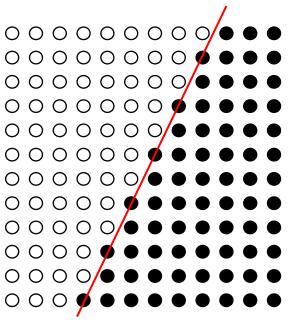


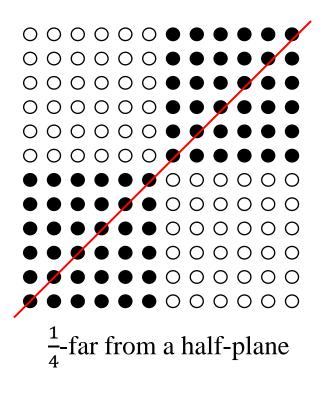


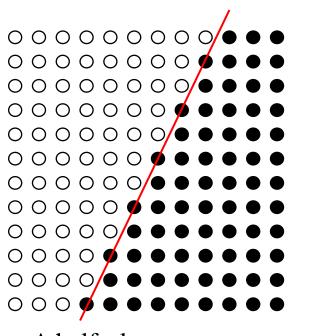


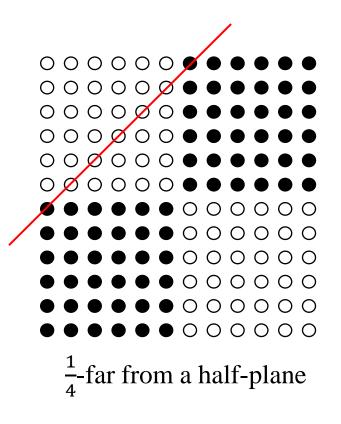










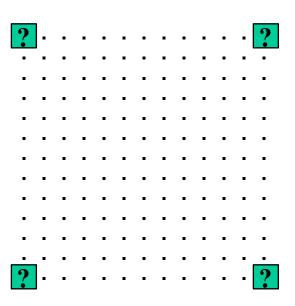


"Testing by implicit learning" paradigm

- Learn the outline of the image by querying a few pixels.
- Test if the image conforms to the outline by random sampling, and reject if something is wrong.

#### Half-plane Test

Claim. The number of sides with different corners is 0, 2, or 4.



#### Algorithm

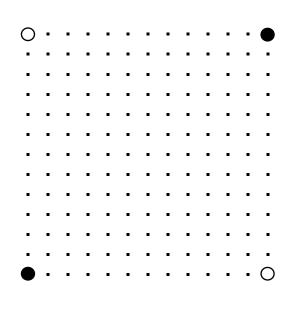
1. Query the corners.

## Half-plane Test: 4 Bi-colored Sides

Claim. The number of sides with different corners is 0, 2, or 4.

#### Analysis

• If it is 4, the image cannot be a half-plane.



#### Algorithm

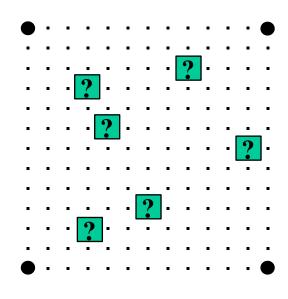
- 1. Query the corners.
- 2. If the number of sides with different corners is 4, reject.

## Half-plane Test: 0 Bi-colored Sides

Claim. The number of sides with different corners is 0, 2, or 4.

#### Analysis

• If all corners have the same color, the image is a half-plane if and only if it is unicolored.



#### Algorithm

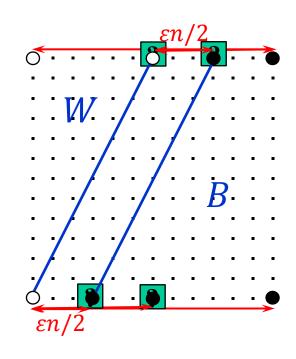
- 1. Query the corners.
- If all corners have the same color c, test if all pixels have color c (as in Toy Example 1).

## Half-plane Test: 2 Bi-colored Sides

Claim. The number of sides with different corners is 0, 2, or 4.

#### Analysis

- The area outside of  $W \cup B$  has  $\leq \epsilon n^2/2$  pixels.
- If the image is a half-plane, W contains only white pixels and B contains only black pixels.
- If the image is  $\varepsilon$ -far from half-planes, it has  $\ge \varepsilon n^2/2$  wrong pixels in  $W \cup B$ .
- By Witness Lemma, 4/ε samples suffice to catch a wrong pixel.

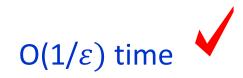


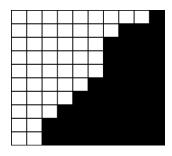
#### Algorithm

- 1. Query the corners.
- 2. If # of sides with different corners is 2, on both sides find 2 different pixels within distance  $\epsilon n/2$  by binary search.
- 3. Query  $4/\varepsilon$  pixels from  $W \cup B$
- 4. Accept iff all *W* pixels are white and all *B* pixels are black.

#### Testing if an Image is a Half-plane [R03]

A half-plane or  $\varepsilon$ -far from a half-plane?





## **Other Results on Properties of Images**

• Pixel Model

**Convexity** [Berman Murzabulatov R] Convex or  $\varepsilon$ -far from convex? O(1/ $\varepsilon$ ) time

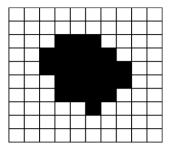
**Connectedness** [Berman Murzabulatov R] Connected or  $\varepsilon$ -far from connected? O( $1/\varepsilon^{3/2} \sqrt{\log 1/\varepsilon}$ ) time

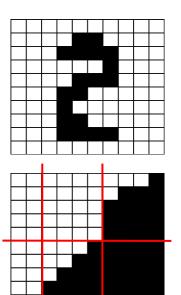
#### Partitioning [Kleiner Keren Newman 10]

Can be partitioned according to a template or is  $\varepsilon$ -far?

time independent of image size

• Properties of sparse images [Ron Tsur 10]





#### Testing if a List is Sorted

Input: a list of *n* numbers  $x_1, x_2, ..., x_n$ 

- Question: Is the list sorted?
   Requires reading entire list: Ω(n) time
- Approximate version: Is the list sorted or ε-far from sorted? (An ε fraction of x<sub>i</sub>'s have to be changed to make it sorted.) [Ergün Kannan Kumar Rubinfeld Viswanathan 98, Fischer 01]: O((log n)/ε) time Ω(log n) queries

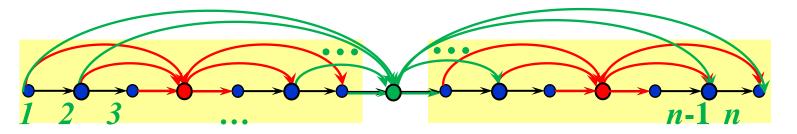


• Attempts:

- $\leftarrow$  1/2-far from sorted
- 2. Test: Pick random i < j and reject if  $x_i > x_j$ . Fails on: 10213243546576

 $\leftarrow$  1/2-far from sorted

Idea: Associate positions in the list with vertices of the directed line.



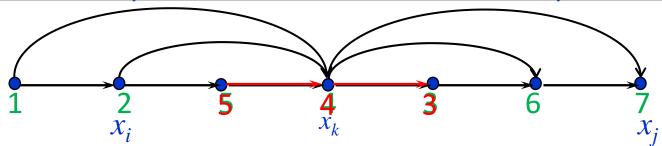
Construct a graph (2-spanner)

 $\leq n \log n$  edges

- by adding a few "shortcut" edges (*i*, *j*) for *i* < *j*
- where each pair of vertices is connected by a path of length at most 2

Test [Dodis Goldreich Lehman Raskhodnikova Ron Samorodnitsky 99]

Pick a random edge  $(x_i, x_j)$  from the 2-spanner and **reject** if  $x_i > x_j$ .



#### Analysis:

- Call an edge  $(x_i, x_j)$  violated if  $x_i > x_j$ , and good otherwise.
- If x<sub>i</sub> is an endpoint of a **violated** edge, call it **bad**. Otherwise, call it **good**.

Claim 1. All good numbers x<sub>i</sub> are sorted.

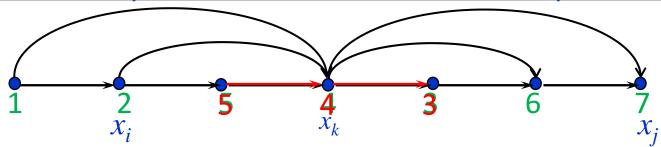
*Proof:* Consider any two good numbers,  $x_i$  and  $x_j$ .

They are connected by a path of (at most) two **good** edges  $(x_i, x_k)$ ,  $(x_k, x_j)$ .  $\Rightarrow x_i \le x_k$  and  $x_k \le x_j$ 

 $\Rightarrow x_i \leq x_j$ 

Test [Dodis Goldreich Lehman Raskhodnikova Ron Samorodnitsky 99]

Pick a random edge  $(x_i, x_i)$  from the 2-spanner and **reject** if  $x_i > x_i$ .



#### Analysis:

- Call an edge  $(x_i, x_j)$  violated if  $x_i > x_j$ , and good otherwise.
- If  $x_i$  is an endpoint of a **bad** edge, call it **bad**. Otherwise, call it **good**.

Claim 1. All good numbers x<sub>i</sub> are sorted.

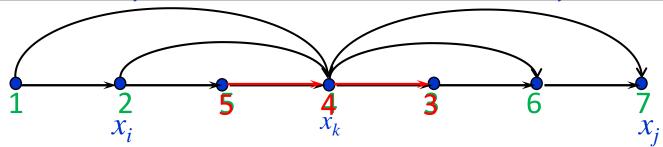
**Claim 2.** An  $\epsilon$ -far list violates  $\geq \epsilon / (2 \log n)$  fraction of edges in 2-spanner.

*Proof:* If a list is  $\epsilon$ -far from sorted, it has  $\geq \epsilon n$  bad numbers. (Claim 1)

- Each violated edge contributes 2 bad numbers.
- 2-spanner has  $\geq \epsilon n/2$  violated edges out of  $\leq n \log n$ .

**Test** [Dodis Goldreich Lehman Raskhodnikova Ron Samorodnitsky 99]

Pick a random edge  $(x_i, x_i)$  from the 2-spanner and **reject** if  $x_i > x_i$ .



#### Analysis:

• Call an edge  $(x_i, x_j)$  violated if  $x_i > x_j$ , and good otherwise.

Claim 2. An  $\epsilon$ -far list violates  $\geq \epsilon / (2 \log n)$  fraction of edges in 2-spanner.

By Witness Lemma, it suffices to sample  $(4 \log n)/\epsilon$  edges from 2-spanner.

Algorithm

Sample (4 log n)/  $\epsilon$  edges ( $x_i, x_i$ ) from the 2-spanner and reject if  $x_i > x_i$ .

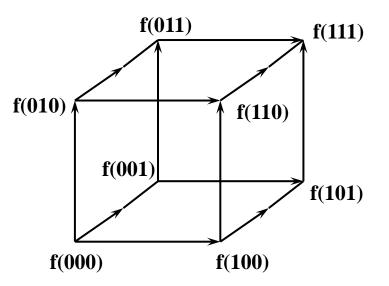
*Guarantee:* All sorted lists are accepted.

All lists that are  $\epsilon$ -far from sorted are rejected with probability  $\geq 2/3$ . Time: O((log n)/ $\epsilon$ )

# Basic Properties of Functions

# Boolean Functions $f : \{0, 1\}^n \rightarrow \{0, 1\}$

Graph representation: *n*-dimensional hypercube



011001

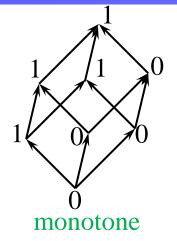
y

- vertices: bit strings of length *n*
- edges: (x, y) is an edge if y can be obtained from x by increasing one bit from 0 to 1 x 001001
- each vertex x is labeled with f(x)

### Monotonicity of Functions

[Goldreich Goldwasser Lehman Ron Samorodnitsky, Dodis Goldreich Lehman Raskhodnikova Ron Samorodnitsky Fischer Lehman Newman Raskhodnikova Rubinfeld Samorodnitsky]

A function f : {0,1}<sup>n</sup> → {0,1} is monotone
 if increasing a bit of x does not decrease f(x).



• Is f monotone or  $\varepsilon$ -far from monotone

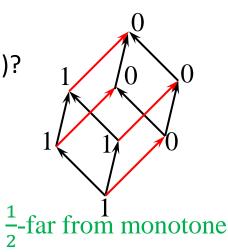
(f has to change on many points to become monontone)?

- Edge  $x \rightarrow y$  is violated by f if f(x) > f(y).

Time:

- $O(n/\varepsilon)$ , logarithmic in the size of the input,  $2^n$
- $\Omega(\sqrt{n}/\varepsilon)$  for restricted class of tests
- Recent:  $\Theta(\sqrt{n}/\varepsilon^2)$  for nonadaptive tests

[Khot Minzer Safra 15, Chen De Servidio Tang 15]



#### Monotonicity Test [GGLRS, DGLRRS]

Idea: Show that functions that are far from monotone violate many edges.

EdgeTest (f, ε)

- 1. Pick  $2n/\epsilon$  edges (x, y) uniformly at random from the hypercube.
- **2.** Reject if some (x, y) is violated (i.e. f(x) > f(y)). Otherwise, accept.

#### Analysis

- If *f* is monotone, **EdgeTest** always accepts.
- If f is  $\varepsilon$ -far from monotone, by Witness Lemma, it suffices to show that  $\geq \varepsilon/n$  fraction of edges (i.e.,  $\frac{\varepsilon}{n} \cdot 2^{n-1}n = \varepsilon 2^{n-1}$  edges) are violated by f.

- Let V(f) denote the number of edges violated by f.

Contrapositive: If  $V(f) < \varepsilon 2^{n-1}$ ,

f can be made monotone by changing  $< \varepsilon 2^n$  values.

Repair Lemma

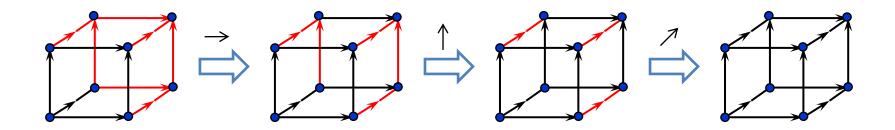
f can be made monotone by changing  $\leq 2 \cdot V(f)$  values.

#### Repair Lemma: Proof Idea

**Repair Lemma** 

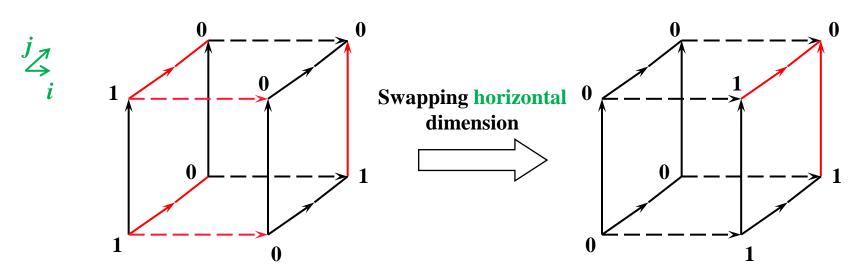
f can be made monotone by changing  $\leq 2 \cdot V(f)$  values.

Proof idea: Transform *f* into a monotone function by repairing edges in one dimension at a time.



#### **Repairing Violated Edges in One Dimension**

Swap violated edges  $1 \rightarrow 0$  in one dimension to  $0 \rightarrow 1$ .

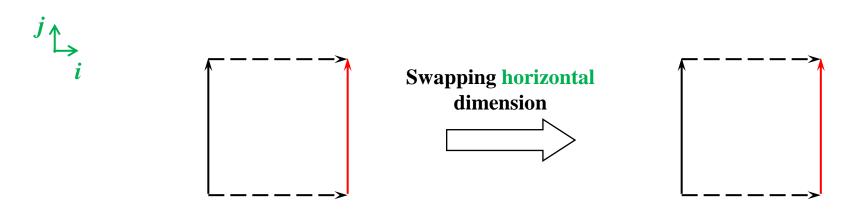


Let  $V_j$  = # of violated edges in dimension j

**Claim.** Swapping in dimension *i* does not increase  $V_i$  for all dimensions  $j \neq i$ 

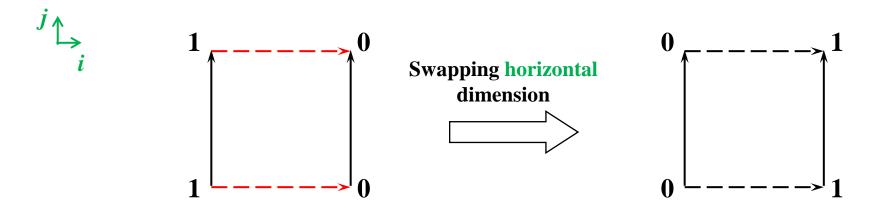
Enough to prove the claim for squares

**Claim.** Swapping in dimension *i* does not increase  $V_i$  for all dimensions  $j \neq i$ 



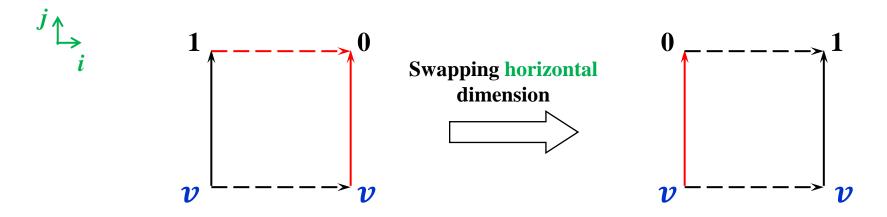
• If no horizontal edges are violated, no action is taken.

**Claim.** Swapping in dimension *i* does not increase  $V_i$  for all dimensions  $j \neq i$ 



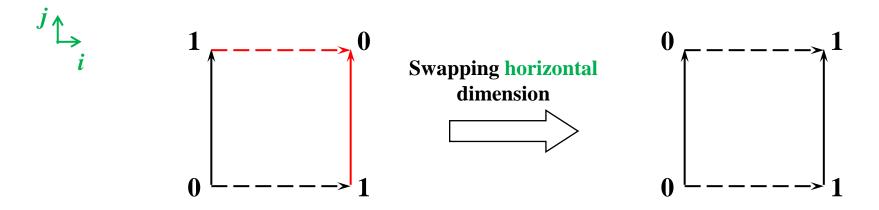
• If both horizontal edges are violated, both are swapped, so the number of vertical violated edges does not change.

**Claim.** Swapping in dimension *i* does not increase  $V_i$  for all dimensions  $j \neq i$ 



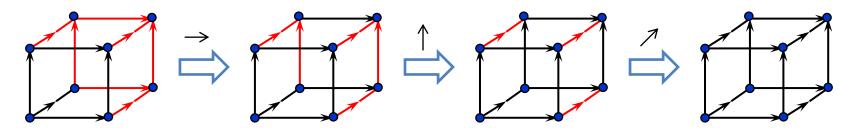
- Suppose one (say, top) horizontal edge is violated.
- If both bottom vertices have the same label, the vertical edges get swapped.

**Claim.** Swapping in dimension *i* does not increase  $V_i$  for all dimensions  $j \neq i$ 



- Suppose one (say, top) horizontal edge is violated.
- If both bottom vertices have the same label, the vertical edges get swapped.
- Otherwise, the bottom vertices are labeled 0→1, and the vertical violation is repaired.

**Claim.** Swapping in dimension *i* does not increase  $V_j$  for all dimensions  $j \neq i$ 



After we perform swaps in all dimensions:

- *f* becomes monotone
- # of values changed:

 $2 \cdot V_1 + 2 \cdot (\# \text{ violated edges in dim 2 after swapping dim 1})$ + 2 \cdot (# violated edges in dim 3 after swapping dim 1 and 2) + ...  $\leq 2 \cdot V_1 + 2 \cdot V_2 + \cdots 2 \cdot V_n = 2 \cdot V(f)$ 

**Repair Lemma** 

f can be made monotone by changing  $\leq 2 \cdot V(f)$  values.

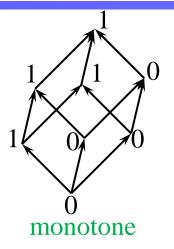


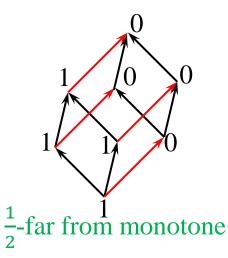
Improve the bound by a factor of 2.

#### Testing if a Functions $f : \{0,1\}^n \rightarrow \{0,1\}$ is monotone

Monotone or  $\varepsilon$ -far from monotone?

O(n/ε) time (logarithmic in the size of the input)



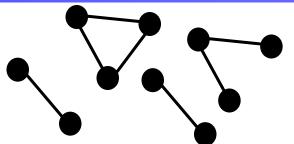


#### **Graph Properties**

# Testing if a Graph is Connected [Goldreich Ron]

Input: a graph G = (V, E) on n vertices

in adjacency lists representation
 (a list of neighbors for each vertex)



- maximum degree d, i.e., adjacency lists of length d with some empty entries Query (v, i), where  $v \in V$  and  $i \in [d]$ : entry i of adjacency list of vertex vExact Answer:  $\Omega(dn)$  time
- Approximate version:

Is the graph connected or  $\epsilon$ -far from connected? dist $(G_1, G_2) = \frac{\# \ of \ entires \ in \ adjacency \ lists \ on \ which \ G_1 \ and \ G_2 \ differ}{dn}$ Time:  $O\left(\frac{1}{\varepsilon^2 d}\right)$  today

#### **Testing Connectedness: Algorithm**

#### Connectedness Tester(G, d, ε)

- **1. Repeat** s=8/ɛd times:
- 2. pick a random vertex *u*
- 3. determine if connected component of *u* is small:

perform BFS from *u*, stopping after at most 4/ɛd new nodes

4. Reject if a small connected component was found, otherwise accept.

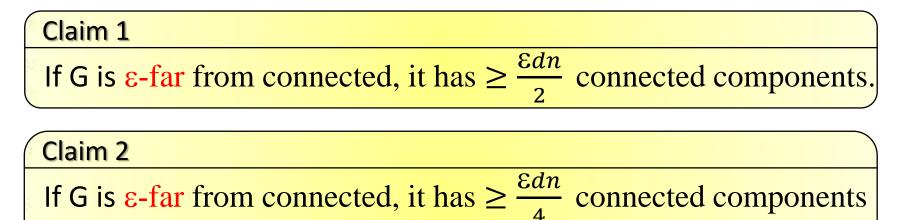
Run time:  $O(d/\epsilon^2 d^2) = O(1/\epsilon^2 d)$ 

#### Analysis:

- Connected graphs are always accepted.
- Remains to show:

If a graph is  $\epsilon$ -far from connected, it is rejected with probability  $\geq \frac{2}{2}$ 

#### **Testing Connectedness: Analysis**



• If Claim 2 holds, at least  $\frac{\mathcal{E}dn}{4}$  nodes are in small connected components.

• By Witness lemma, it suffices to sample  $\frac{2 \cdot 4}{\epsilon dn/n} = \frac{8}{\epsilon d}$  nodes to detect one from a small connected component.

### **Testing Connectedness: Proof of Claim 1**

Claim 1	
If G is $\frac{\varepsilon - far}{2}$ from connected, it has $\geq \frac{\varepsilon dn}{2}$ connected compo	nents.

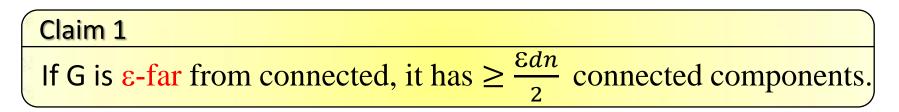
We prove the **contrapositive**:

If G has  $<\frac{\varepsilon dn}{2}$  connected components, one can make G connected by modifying  $< \varepsilon$  fraction of its representation, i.e.,  $< \varepsilon dn$  entries.

- If there are no degree restrictions, k components can be connected by adding k-1 edges, each affecting 2 nodes. Here,  $k < \frac{\varepsilon dn}{2}$ , so  $2k-2 < \varepsilon dn$ .
- What if adjacency lists of all vertices in a component are full,

i.e., all vertex degrees are d?

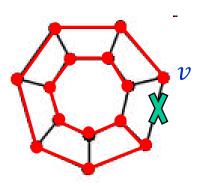
### Freeing up an Adjacency List Entry



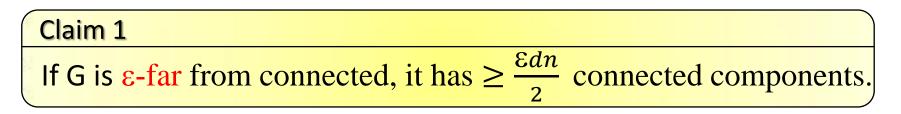
What if adjacency lists of all vertices in a component are full,

i.e., all vertex degrees are d?

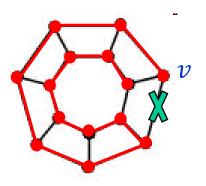
- Consider an MST of this component.
- Let v be a leaf of the MST.
- Disconnect v from a node other than its parent in the MST.
- Two entries are changed while keeping the same number of components.



#### Freeing up an Adjacency List Entry



What if adjacency lists of all vertices in a component are full, i.e., all vertex degrees are d?



- Apply this to each component that <2 free spots in adjacency lists.
- Now we can connect all the components using the freed up spots while ensuring that we never change more than 2 spots per component.
- Thus, k components can be connected by changing 2k spots.

Here, 
$$k < \frac{\varepsilon dn}{4}$$
, so  $2k < \varepsilon dn$ .

### **Testing Connectedness: Proof of Claim 2**

Claim 1 If G is  $\varepsilon$ -far from connected, it has  $\geq \frac{\varepsilon dn}{2}$  connected components.

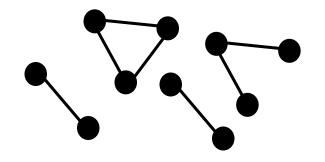
Claim 2 If G is  $\epsilon$ -far from connected, it has  $\geq \frac{\epsilon dn}{4}$  connected components of size at most 4/ $\epsilon$ d.

- If Claim 1 holds, there are at least  $\frac{\varepsilon dn}{2}$  connected components.
- Their average size  $\leq \frac{n}{\epsilon dn/2} = \frac{2}{\epsilon d}$ .
- By an averaging argument (or Markov inequality), at least half of the components are of size at most twice the average.

#### Testing if a Graph is Connected [Goldreich Ron]

Input: a graph G = (V, E) on n vertices

- in adjacency lists representation
   (a list of neighbors for each vertex)
- maximum degree *d*



Connected or

 $\varepsilon$ -far from connected?

$$O\left(\frac{1}{\varepsilon^2 d}\right)$$
 time (no dependence on  $n$ )

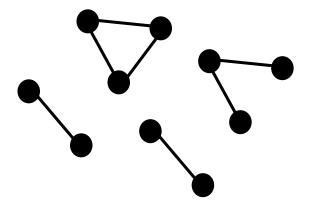
# Approximating # of Connected Components

[Chazelle Rubinfeld Trevisan]

Input: a graph G = (V, E) on **n** vertices

- in adjacency lists representation
   (a list of neighbors for each vertex)
- maximum degree *d*

Exact Answer:  $\Omega(dn)$  time Additive approximation: # of CC ± $\epsilon$ n with probability  $\geq 2/3$ 



Time:

- Known:  $O\left(\frac{d}{\epsilon^2}\log\frac{1}{\epsilon}\right), \Omega\left(\frac{d}{\epsilon^2}\right)$
- Today:  $O\left(\frac{d}{\varepsilon^3}\right)$ .



Partially based on slides by Ronitt Rubinfeld: http://stellar.mit.edu/S/course/6/fa10/6.896/courseMaterial/topics/topic3/lectureNotes/lecst11/lecst11.pdf

# Approximating # of CCs: Main Idea

- Let *C* = number of components
- For every vertex u, define  $n_u$  = number of nodes in u's component Breaks C up into
  - for each component **A**:  $\sum_{u \in A} \frac{1}{n_u} = 1$  $\sum_{u \in V} \frac{1}{n_u} = C$
- Estimate this sum by estimating  $n_u$ 's for a few random nodes
  - If u's component is small, its size can be computed by BFS.
  - If u's component is big, then  $1/n_u$  is small, so it does not contribute much to the sum
  - Can stop BFS after a few steps

Similar to property tester for connectedness [Goldreich Ron]

contributions

<u>of</u> different nodes

# Approximating # of CCs: Algorithm

Estimating  $n_u$  = the number of nodes in u's component:

Let estimate  $\hat{n}_u = \min\left\{n_u, \frac{2}{c}\right\}$ •

- $\text{ When } u \text{'s component has } \leq 2/\epsilon \text{ nodes }, \hat{n}_u = n_u \\ \text{ Else } \hat{n}_u = 2/\epsilon, \text{ and so } 0 < \frac{1}{\hat{n}_u} \frac{1}{n_u} < \frac{1}{\hat{n}_u} = \frac{\epsilon}{2} \\ \end{array} \right\} \left| \frac{1}{\hat{n}_u} \frac{1}{n_u} \right| \leq \frac{\epsilon}{2}$
- Corresponding estimate for C is  $\hat{C} = \sum_{u \in V} \frac{1}{\hat{n}_{u}}$ . It is a good estimate:

$$\left| \hat{C} - C \right| = \left| \sum_{u \in V} \frac{1}{\hat{n}_u} - \sum_{u \in V} \frac{1}{n_u} \right| \le \sum_{u \in V} \left| \frac{1}{\hat{n}_u} - \frac{1}{n_u} \right| \le \frac{\varepsilon n}{2}$$

´APPROX\_#\_CCs (G, d, ε)

- **Repeat**  $s=\Theta(1/\epsilon^2)$  times: 1.
- pick a random vertex u 2.
- compute  $\hat{n}_u$  via BFS from u, stopping after at most  $2/\epsilon$  new nodes 3.
- **Return**  $\tilde{C}$  = (average of the values  $1/\hat{n}_{\mu}$ )  $\cdot n$ 4.

#### Run time: O(d $/\epsilon^3$ )

### Approximating # of CCs: Analysis

Want to show: 
$$\Pr\left[\left|\tilde{C} - \hat{C}\right| > \frac{\varepsilon n}{2}\right] \le \frac{1}{3}$$

#### **Hoeffding Bound**

Let  $Y_1, ..., Y_s$  be independently distributed random variables in [0,1] and let  $Y = \sum_{i=1}^{s} Y_i$  (sample sum). Then  $\Pr[|Y - E[Y]| \ge \delta] \le 2e^{-2\delta^2/s}$ .

Let  $Y_i = 1/\hat{n}_u$  for the i<sup>th</sup> vertex u in the sample

• 
$$\mathbf{Y} = \sum_{i=1}^{s} \mathbf{Y}_{i} = \frac{s\tilde{c}}{n}$$
 and  $\mathbf{E}[\mathbf{Y}] = \sum_{i=1}^{s} \mathbf{E}[\mathbf{Y}_{i}] = s \cdot \mathbf{E}[\mathbf{Y}_{1}] = s \cdot \frac{1}{n} \sum_{u \in V} \frac{1}{\hat{n}_{u}} = \frac{s\hat{c}}{n}$   
 $\Pr\left[\left|\tilde{c} - \hat{c}\right| > \frac{\varepsilon n}{2}\right] = \Pr\left[\left|\frac{n}{s}\mathbf{Y} - \frac{n}{s}\mathbf{E}[\mathbf{Y}]\right| > \frac{\varepsilon n}{2}\right] = \Pr\left[|\mathbf{Y} - \mathbf{E}[\mathbf{Y}]| > \frac{\varepsilon s}{2}\right] \le 2e^{-\frac{\varepsilon^{2}s}{2}}$   
• Need  $s = \Theta\left(\frac{1}{\varepsilon^{2}}\right)$  samples to get probability  $\le \frac{1}{3}$ 

#### Approximating # of CCs: Analysis

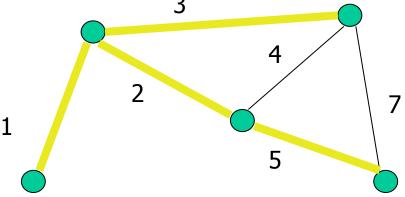
So far: 
$$|\hat{C} - C| \leq \frac{\varepsilon n}{2}$$
  
 $\Pr\left[|\tilde{C} - \hat{C}| > \frac{\varepsilon n}{2}\right] \leq \frac{1}{3}$   
• With probability  $\geq \frac{2}{3}$ ,  
 $|\tilde{C} - C| \leq |\tilde{C} - \hat{C}| + |\hat{C} - C| \leq \frac{\varepsilon n}{2} + \frac{\varepsilon n}{2} \leq \varepsilon n$ 

#### Summary:

The number of connected components in *n*-vetex graphs of degree at most *d* can be estimated within  $\pm \varepsilon n$  in time  $O\left(\frac{d}{\varepsilon^3}\right)$ .

#### Minimum spanning tree (MST)

What is the cheapest way to connect all the dots?
 Input: a weighted graph
 with n vertices and m edges
 3



- Exact computation:
  - Deterministic  $O(m \cdot \text{inverse-Ackermann}(m))$  time [Chazelle]
  - Randomized O(m) time [Karger Klein Tarjan]

# Approximating MST Weight in Sublinear Time

[Chazelle Rubinfeld Trevisan]

Input: a graph G = (V, E) on n vertices

- in adjacency lists representation
- maximum degree *d* and maximum allowed weight *w*
- weights in {1,2,...,w}

Output:  $(1 + \varepsilon)$ -approximation to MST weight,  $w_{MST}$ 

Time:

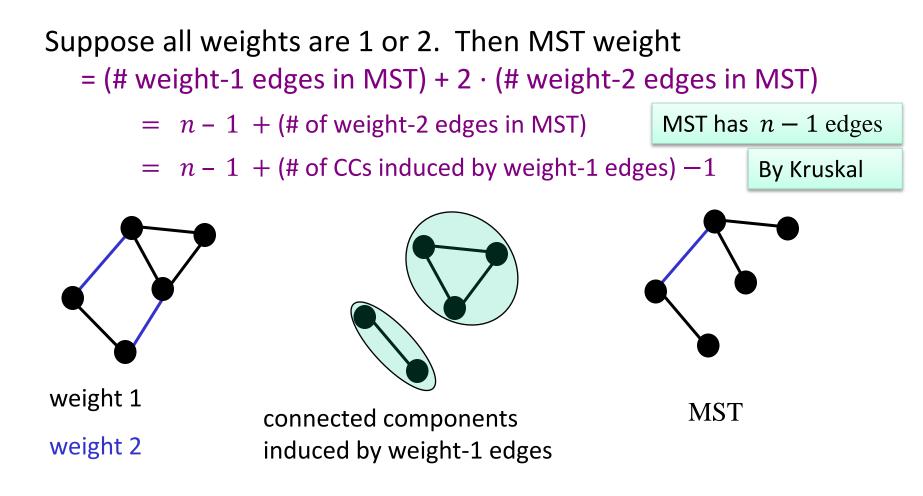
- Known:  $O\left(\frac{dw}{\varepsilon^3}\log\frac{dw}{\varepsilon}\right), \Omega\left(\frac{dw}{\varepsilon^2}\right)$
- Today:  $O\left(\frac{dw^4 \log w}{\varepsilon^3}\right)$



- Characterize MST weight in terms of number of connected components in certain subgraphs of *G*
- Already know that number of connected components can be estimated quickly

#### MST and Connected Components: Warm-up

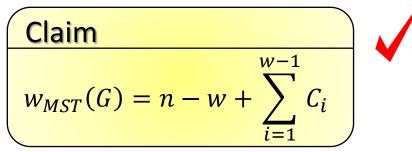
Recall Kruskal's algorithm for computing MST exactly.



#### **MST and Connected Components**

In general: Let  $G_i$  = subgraph of G containing all edges of weight  $\leq i$  $C_i$  = number of connected components in  $G_i$ 

Then MST has  $C_i - 1$  edges of weight > i.



- Let  $\beta_i$  be the number of edges of weight > *i* in MST
- Each MST edge contributes 1 to  $w_{MST}$ , each MST edge of weight >1 contributes 1 more, each MST edge of weight >2 contributes one more, ...

$$w_{MST}(G) = \sum_{i=0}^{w-1} \beta_i = \sum_{i=0}^{w-1} (C_i - 1) = -w + \sum_{i=0}^{w-1} C_i = n - w + \sum_{i=1}^{w-1} C_i$$

# Algorithm for Approximating W<sub>MST</sub>

APPROX\_MSTweight (G, w, d, ε)

- **1.** For i = 1 to w 1 do:
- 2.  $\tilde{C}_i \leftarrow \text{APPROX}_{\#\text{CCs}}(G_i, d, \varepsilon/w).$
- **3.** Return  $\widetilde{w}_{MST} = n w + \sum_{i=1}^{w-1} \widetilde{C}_i$ .

Analysis:

• Suppose all estimates of  $C_i$ 's are good:  $|\tilde{C}_i - C_i| \leq \frac{\varepsilon}{w} n$ .

Then  $|\widetilde{w}_{MST} - w_{MST}| = |\sum_{i=1}^{w-1} (\widetilde{C}_i - C_i)| \le \sum_{i=1}^{w-1} |\widetilde{C}_i - C_i| \le w \cdot \frac{\varepsilon}{w} n = \varepsilon n$ 

- Pr[all w 1 estimates are good]  $\geq (2/3)^{w-1}$
- Not good enough! Need error probability  $\leq \frac{1}{3w}$  for each iteration
- Then, by Union Bound,  $\Pr[\text{error}] \le w \cdot \frac{1}{3w} = \frac{1}{3}$



Can amplify success probability of any algorithm by repeating it and taking the median answer.

Can take more samples in APPROX\_#CCs. What's the resulting run time?

Claim. 
$$w_{MST}(G) = n - w + \sum_{i=1}^{w-1} C_i$$

#### Multiplicative Approximation for W<sub>MST</sub>

For MST cost, additive approximation  $\Rightarrow$  multiplicative approximation  $w_{MST} \ge n-1 \implies w_{MST} \ge n/2$  for  $n \ge 2$ 

• *ɛn*-additive approximation:

$$w_{MST} - \varepsilon n \le \widehat{w}_{MST} \le w_{MST} + \varepsilon n$$

•  $(1 \pm 2\varepsilon)$ -multiplicative approximation:  $w_{MST}(1 - 2\varepsilon) \le w_{MST} - \varepsilon n \le \widehat{w}_{MST} \le w_{MST} + \varepsilon n \le w_{MST}(1 + 2\varepsilon)$